

Systems and Software Verification

Chapter 3. Model Checking

3. Model Checking

- Motivation:
 - Describe the principles underlying the algorithms used for model checking
 - The algorithm
 - Can find out whether a given automaton satisfies a given temporal formula
 - Different algorithms for CTL and PLTL
- Organization of Chapter 3
 - Model Checking CTL
 - Model Checking PLTL
 - The State Explosion Problem

3.1 Model Checking CTL

- Model checking algorithm for CTL
 - Developed in 1980s
 - Runs in time linear in each of its components (automaton and CTL formula)
 - Relies on the fact that CTL can only express state formulas
- Basic principles
 - procedure **marking**
 - Starting from a CTL formula ϕ
 - Mark for each state q of the automaton and for each sub-formula ψ of ϕ ,
 - Whether ψ is satisfied in state q
- Correctness of the algorithm
 - ...
 - Hence, the marking of q is correct.
- Complexity of the algorithm
 - Model checking " does $A, q_0 \models \phi$? " for a CTL formula ϕ
 - can be solved in time $O(|A| \times |\phi|)$
 - $O(|A|)$: for marking the automaton
 - $O(|\phi|)$: for each sub-formula in ϕ
 - Linear!!!

```
procedure marking(phi)
```

```
  case 1: phi = P
    for all q in Q, if P in l(q) then do q.phi := true,
      else do q.phi := false.
```

```
  case 2: phi = not psi
    do marking(psi);
    for all q in Q, do q.phi := not(q.psi).
```

```
  case 3: phi = psi1 /\ psi2
    do marking(psi1); marking(psi2);
    for all q in Q, do q.phi := and(q.psi1, q.psi2).
```

```
  case 4: phi = EX psi
    do marking(psi);
    for all q in Q, do q.phi := false;      /* initialisation */
    for all (q,q') in T, if q'.psi = true then do q.phi := true.
```

```
  case 5: phi = E psi1 U psi2
    do marking(psi1); marking(psi2);
    for all q in Q,
      q.phi := false; q.seenbefore := false; /* initialisation */
    L := {}; /* L: states to be processed */
    for all q in Q, if q.psi2 = true then do L := L + { q };
    while L nonempty {
      draw q from L; /* must mark q */
      L := L - { q };
      q.phi := true;
      for all (q',q) in T { /* q' is a predecessor of q */
        if q'.seenbefore = false then do {
          q'.seenbefore := true;
          if q'.psi1 = true then do L := L + { q' };
        }
      }
    }
  }
```

```
  case 6: phi = A psi1 U psi2
    do marking(psi1); marking(psi2);
    L := {}; /* L: states to be processed */
    for all q in Q,
      q.nb := degree(q); q.phi := false; /* initialisation */
    for all q in Q, if q.psi2 = true then do L := L + { q };
    while L nonempty {
      draw q from L; /* must mark q */
      L := L - { q };
      q.phi := true;
      for all (q',q) in T { /* q' is a predecessor of q */
        q'.nb := q'.nb - 1; /* decrement */
        if (q'.nb = 0) and (q'.psi1 = true) and (q'.phi = false)
          then do L := L + { q' };
      }
    }
  }
```

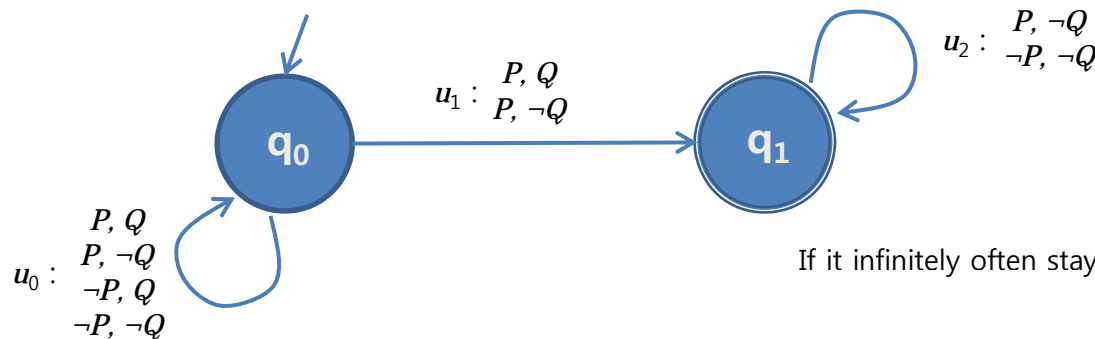
3.2 Model Checking PLTL

- Model checking algorithm for PLTL
 - Developed in 1980s, but too technical to cover in this course
 - PLTL uses path formulas
 - No longer possible to rely on marking the automaton states
 - A finite automaton will generally give rise to infinitely many different executions, themselves often infinite in length
 - Hence, PLTL uses a language theory : ω -regular expression
 - An extension of a regular expression
 - "*" : an arbitrary but finite number of repetitions
 - $(a b^* + c)^*$
 - " ω ": an infinite number of repetitions

- Basic principle
 - Model checking " does $A \models \phi$? " for a PLTL formula ϕ
 - Reduces to a " Are all the execution of A of the form described by ε_ϕ ? "
 - A PLTL model checker construct an automaton $B_{\neg\phi}$ (recognizing executions which do not satisfy ϕ)
 - Strongly synchronize A and $B_{\neg\phi} \rightarrow A \otimes B_{\neg\phi}$
 - Finally reduces to " Is the language recognized by $A \otimes B_{\neg\phi}$ empty ?"

- A simple example

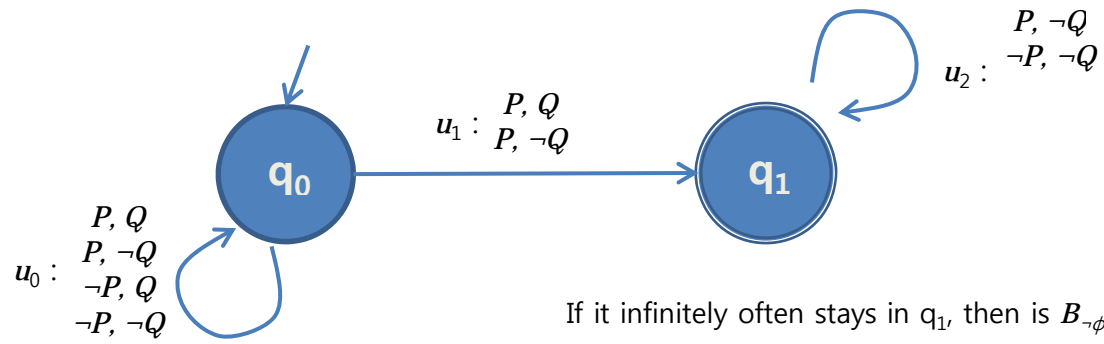
- $\phi : G(P \Rightarrow XF Q)$ \rightarrow any occurrence of P must be followed (later) by an occurrence of Q
- $B_{\neg\phi}$ \rightarrow there exists an occurrence of P after which we will never again encounter Q



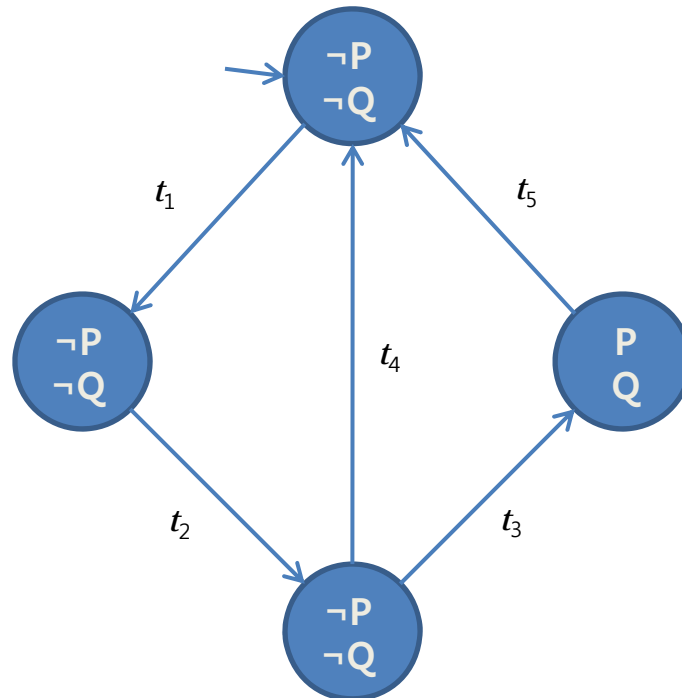
If it infinitely often stays in q_1 , then is $B_{\neg\phi}$ satisfied.

$\phi : G(P \Rightarrow X F Q)$

$B_{\neg\phi} :$

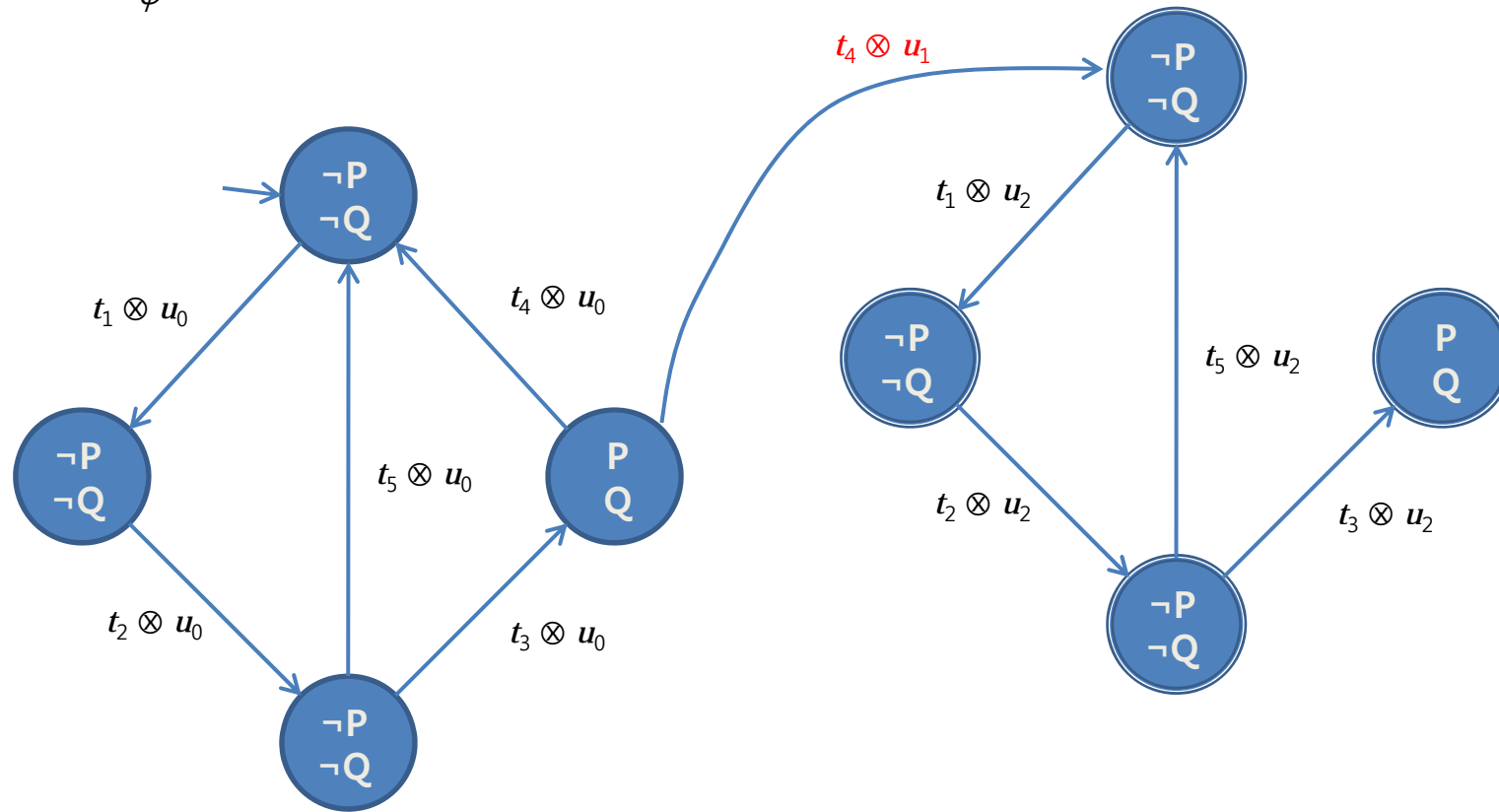


$A :$



" does $A \models \phi$? "

$A \otimes B_{\neg\phi}$:



There are behaviors of A accepted by $A \otimes B_{\neg\phi}$

→ The language recognized by $A \otimes B_{\neg\phi}$ is nonempty

→ $A \not\equiv \phi$

- Construction of $B_{\neg\phi}$
 - Very difficult technically
 - Automaton $B_{\neg\phi}$ must in general be able to recognize infinite words
→ Büchi automata
- Complexity of the algorithm
 - $B_{\neg\phi}$ has size $O(2^{|\phi|})$ in the worst case
 - $A \otimes B_{\neg\phi}$ has size $O(|A| \times |B_{\neg\phi}|)$
 - If $A \otimes B_{\neg\phi}$ fits in computer memory, we can determine it in time $O(|A| \times |B_{\neg\phi}|)$
 - Model checking “does $A, q_0 \models \phi$?” for a PLTL formula ϕ can be done in time $O(|A| \times 2^{|\phi|})$
- Reachability analysis
 - We can say that $B_{\neg\phi}$ observes the behavior of A when the two automata are synchronized.
 - Observable automata = formal specification of the desired property
 - UPPAAL
 - SPIN

3.3 The State Explosion Problem

- State explosion problem
 - The main obstacle encountered by model checking algorithms
 - Indeed, the algorithms rely on explicit construction of the automaton A
 - Traversal and marking (in case of CTL)
 - Synchronization with $B_{\neg\phi}$ and seeking of reachable states and loops (in case of PLTL)
 - In practice, the number of states of A is quickly very large
 - If we use values that are not priori bounded (integers, a waiting queue, etc.), we cannot even apply it
 - Explicit model checking \rightarrow Symbolic model checking (Chapter 4)