

Introduction to Formal Methods

Chapter 7. Safety Properties

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7. Safety Properties

- Safety property
 - Under certain conditions, an (undesirable) event never occur.
 - Examples:
 - (S1) " Both processes will never be in their critical sections simultaneously (mutual exclusion) "
 - (S2) " Memory overflow will never occur "
 - (S3) " The situation ... is impossible "
 - (S4) " As long as the key is not in the ignition position, the car won't start " ← with conditions
 - \neg safety property = reachability property
 - \neg reachability property = safety property
- Organization of Chapter 7
 - Safety Properties in Temporal Logic
 - A Formal Definition
 - Safety Properties in Practice
 - The history Variables Method

7.1 Safety Properties in Temporal Logic

- $AG \phi$
 - “ ϕ never occurs. ”
 - (S1) “ Both processes will never be in their critical sections simultaneously ”
 - $AG \neg(\text{crit_sec}_1 \wedge \text{crit_sec}_2)$
 - (S2) “ Memory overflow will never occur ”
 - $AG \neg\text{overflow}$
 - (S3) “ The situation ... is impossible ”
 - $AG \neg\text{situation}$
 - (S4) “ As long as the key is not in the ignition position, the car won't start ”
 - $A (\neg\text{start} W \text{key})$ (using weak until)
 - $A (\neg\text{start} U \text{key})$ ← Not a safety property !

7.2 A Formal Definition

- Syntactic characterization
 - Safety properties can be written in the form $AG \phi^-$
 - ϕ^- is a past temporal formula
 - When a safety property is violated, it should be possible to instantly notice it.
 - We can only notice it, in the current state, relying on events which occurred earlier.
- Temporal logic with past
 - CTL* does not provide past combinators
 - But, we can use a mirror image of future combinators (F^{-1}, X^{-1})

- AG ϕ^- in practice
 - (S1) AG $\neg(\text{crit_sec}_1 \wedge \text{crit_sec}_2)$
 - $\neg(\text{crit_sec}_1 \wedge \text{crit_sec}_2)$ is a ϕ^-
 - (S4) A $\neg\text{start}$ W key
 - Can be rewritten in the form: AG ($\text{start} \Rightarrow F^{-1} \text{key}$)
 - " It is always true (AG) that if the car starts, then (\Rightarrow) the key was inserted beforehand (F^{-1}). "
 - If ψ_1 and ψ_2 are safety properties, then $\psi_1 \wedge \psi_2$ again a safety property.
 - But, $\psi_1 \vee \psi_2$ is in general not

- Safety properties and diagnostic
 - If AG ϕ^- is not satisfied, then there necessarily exists a finite path leading from *init* to it.
 - Since ϕ^- is a past formula.

7.3 Safety Properties in Practice

- Safety properties are verified simply by submitting it to a model checker.
- But, in real life, hurdles spring up.
- A simple case: non-reachability
 - The most safety properties
 - $\neg EF (\text{crit_in}_1 \wedge \text{crit_in}_2) = AG \phi^-$
 - $\neg(\text{crit_in}_1 \wedge \text{crit_in}_2)$ is a present formula
- Safety without past
 - $A (\neg \text{start} W \text{key})$ is used more often than $AG (\text{start} \Rightarrow F^{-1} \text{key})$
 - But, no model checker is able to deal with past formulas. So, mixed logics are used.
 - The problem is their identification.
 - If they are identified, then it can be dealt with similarly
 - Otherwise, we have to use the method of history variables (in section 7.4)
- Safety with explicit past
 - No model checker is able to handle temporal formula with past.
 - Two approaches:
 1. Eliminate the past (in principle, it is possible to translate mixed formulas to pure-future ones)
 - $AG (\phi \Rightarrow F^{-1} \psi) \equiv A (\neg \phi W \psi)$, but not easy.
 2. History variable method (section 7.4)

7.4 The History Variables Method

- Skipped !!!