



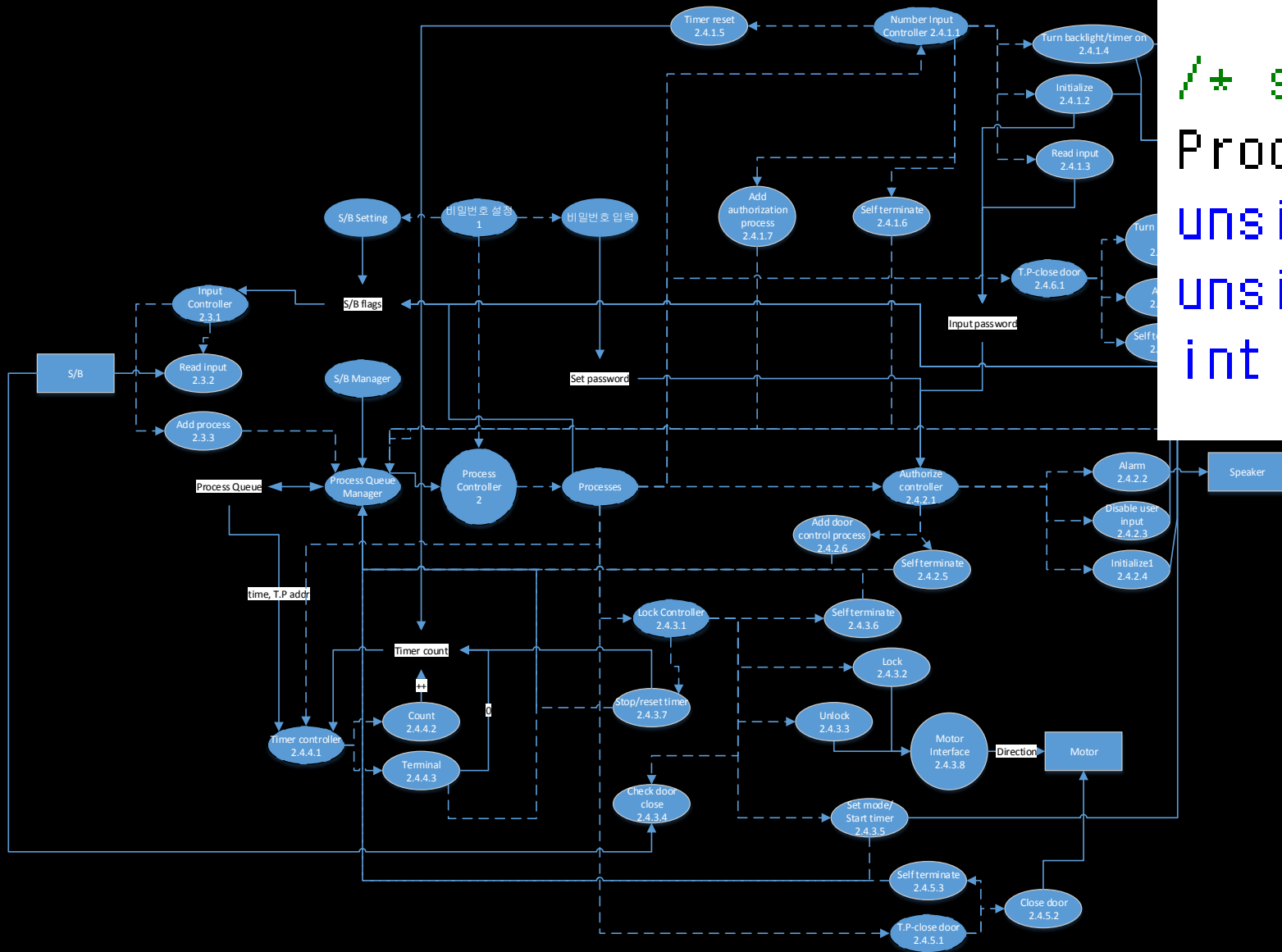
소프트웨어공학개론 Electronic Door Lock System

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Contents

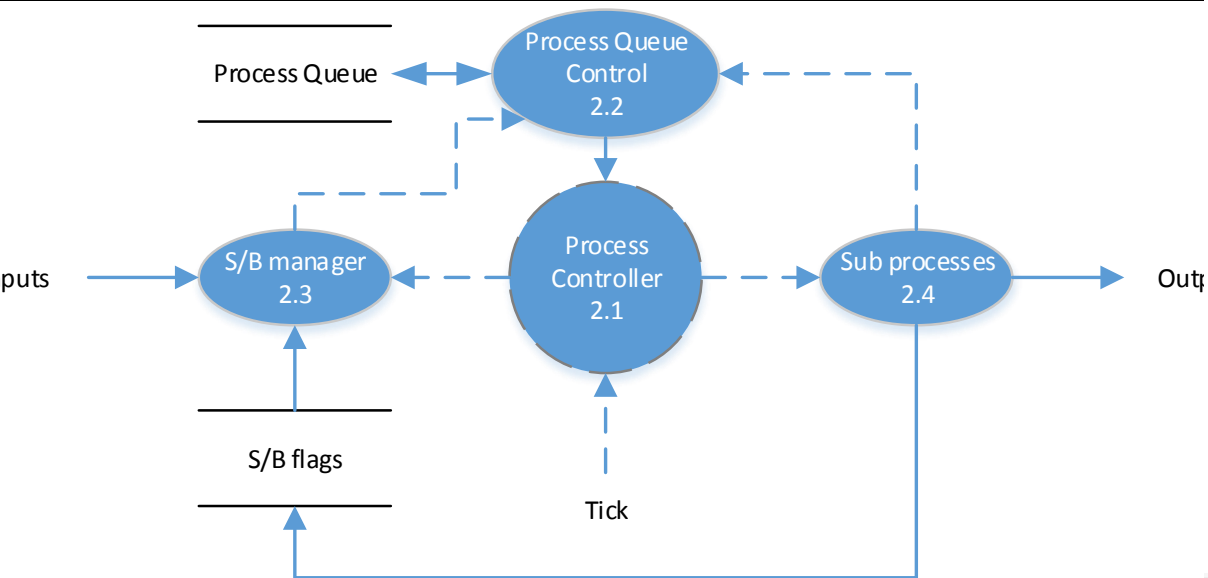
- Singleton 변수
- 메인루프 – 서브프로세스 구조 : Strategy
- 프로세스 큐 : Strategy
- 입력/출력
- 타이머
- 시연
- QNA

Singleton 변수 stdafx.h



```
/* singleton variables */  
ProcessQueue *PQ;  
unsigned *SBFlags;  
unsigned *Pass;  
int MotorDeg;
```

메인루프-서브프로세스 구조 SubProcesses.h / main.c



```
#include "stdafx.h"
```

```
void *SBManager(int arg1, int arg2);
```

```
void *authorize(int arg1, int arg2);
```

```
void *numIn(int comm, int arg2);
```

```
void *doorCtrl(int comm, int arg2);
```

```
void *timer(int time, void(*TP)(int, int));
```

```
void *TPClose(int arg1, int arg2);
```

```
void *TPTBO(int arg1, int arg2);
```

```
while (!GetAsyncKeyState(YK_ESCAPE)){
```

```
    time(&ts);
```

```
    PQ->run( );
```

```
    IOtoFlags(SBFlags);
```

```
    time(&te);
```

```
    timelapse = te - ts;
```

```
    if (timelapse < TICK && timelapse >= 0)
```

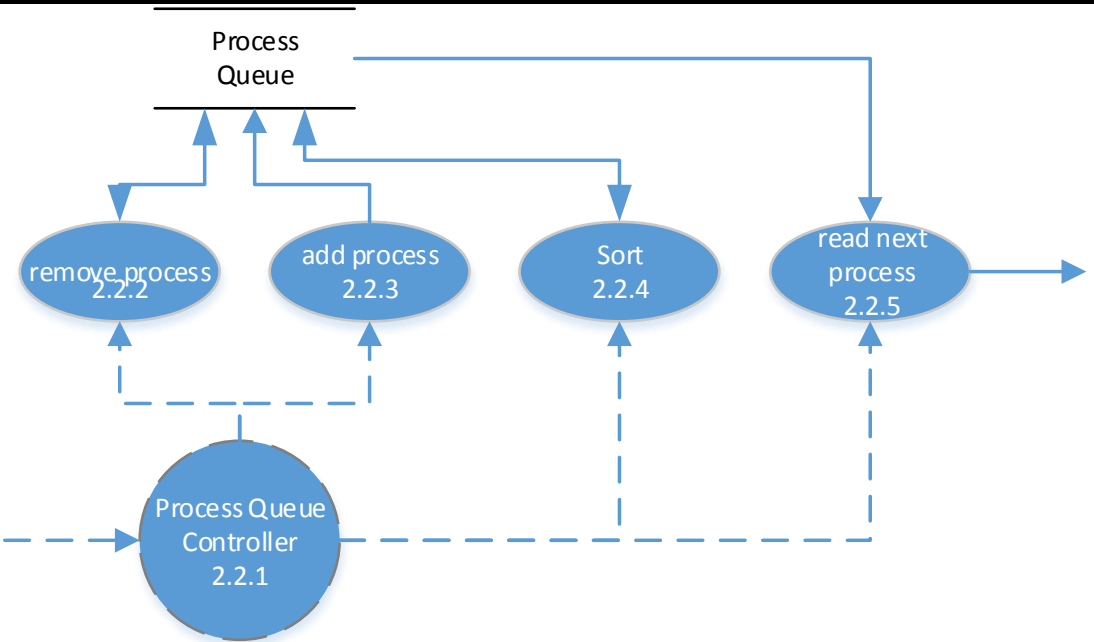
```
        Sleep(TICK - timelapse);
```

```
    else
```

```
        printf("#n#####runtime calculation error#####
```

```
}
```

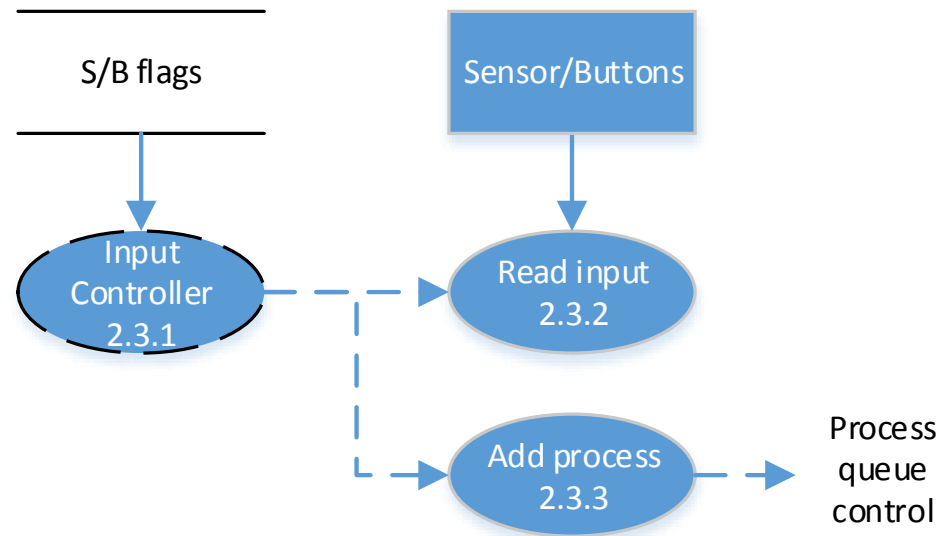
프로세스 큐 ProcessQueue.h



```
typedef struct _ProcessQueue{
    int (*size)();
    void (*add)(void *, int, int);
    void(*run)();
    ProcessNode *(*find)(void *, int, int);
    void(*editArg)(void *, int, int, int, int);
    void(*del)(void *);
    void(*findDel)(void *, int, int);
    ProcessLinkedList list;
}ProcessQueue;

void initPQ();
static void *add(void *, int arg1, int arg2);
static void *addNode(ProcessNode *n);
static int size();
static void *run();
static ProcessNode *find(void *addr, int arg1, int arg2);
static void *editArg(void *addr, int arg1, int arg2, int narg1, int narg2);
static void *del(void *addr);
static void *findDel(void *addr, int arg1, int arg2);
```

입력/출력 stdafx.h/hexUtil.h



```
/* Sensor/Buttons */  
//door button  
#define DB 0  
//cover sensor  
#define CS 1  
//key sensor  
#define KS 2  
//door clasion sensor  
#define DS 3
```

```
/* number buttons */  
#define B0 4  
#define B1 5  
#define B2 6  
#define B3 7  
#define B4 8  
#define B5 9  
#define B6 10  
#define B7 11  
#define B8 12  
#define B9 13
```

```
/* Actuators */  
//back light  
#define BL 14  
//motor  
#define MT 15  
//speaker  
#define SP 16
```

```
#define MASK 17  
#define TICK 100
```

```
BitClr(SBFlags, DB);
```

```
BitClr(SBFlags, BO + MASK + i);
```

```
//MSB부터 비어있는(F) 비트의 인덱스를 찾아 반환  
int findHexBlank(unsigned *val);
```

```
//MSB부터 비어있는(F) 비트를 in으로 채운다.  
//in:0~9
```

```
void putHexInBlank(unsigned *val, int in);
```

```
//pos 인덱스의 비트를 0으로 설정한다.  
//pos:0-31
```

```
void BitClr(unsigned *trg, unsigned pos);
```

```
//pos 인덱스의 비트를 1로 설정한다.  
//pos:0-31
```

```
void BitSet(unsigned *trg, unsigned pos);
```

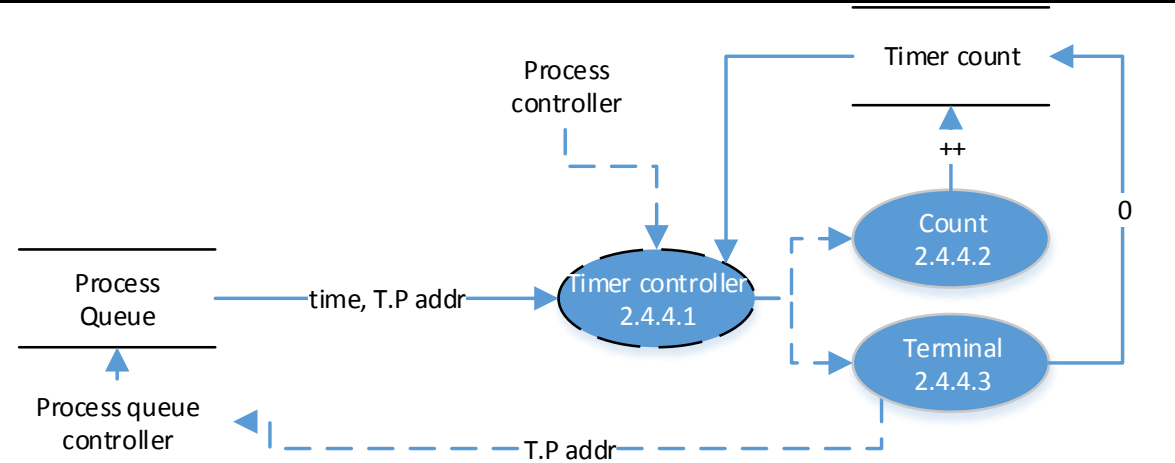
```
//pos 인덱스의 비트를 반환한다.  
//pos:0-31
```

```
int BitGet(unsigned *trg, unsigned pos);
```

타이머

```
PQ->add(timer, 3 * TPS, TPClose); //start timer
```

```
void *timer(int time, void(*TP)(int, int)){  
    PQ->editArg(timer, time, TP, time - 1, TP);  
    if (time <= 0){  
        PQ->add(TP, 0, 0);  
        PQ->del(timer);  
    }  
}
```



시연

실행

QNA